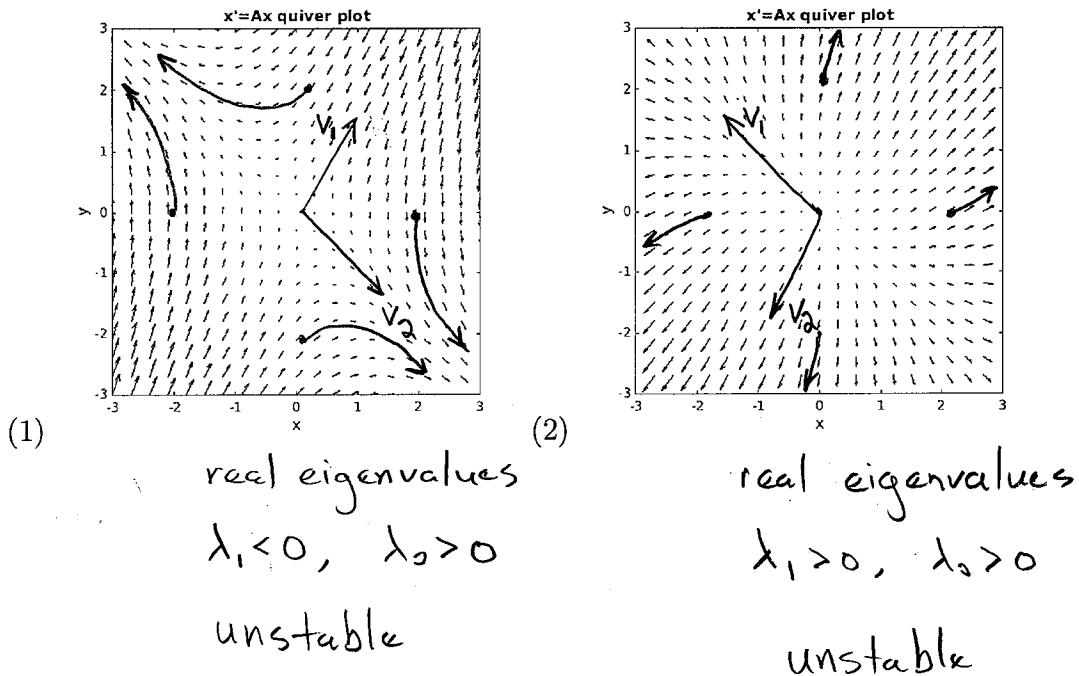


Problems 1-6. The following plots show arrows $\mathbf{x}' = d\mathbf{x}/dt$ for linear systems. $\mathbf{x}' = A\mathbf{x}$. In each case, A has distinct eigenvalues and two eigenvectors.

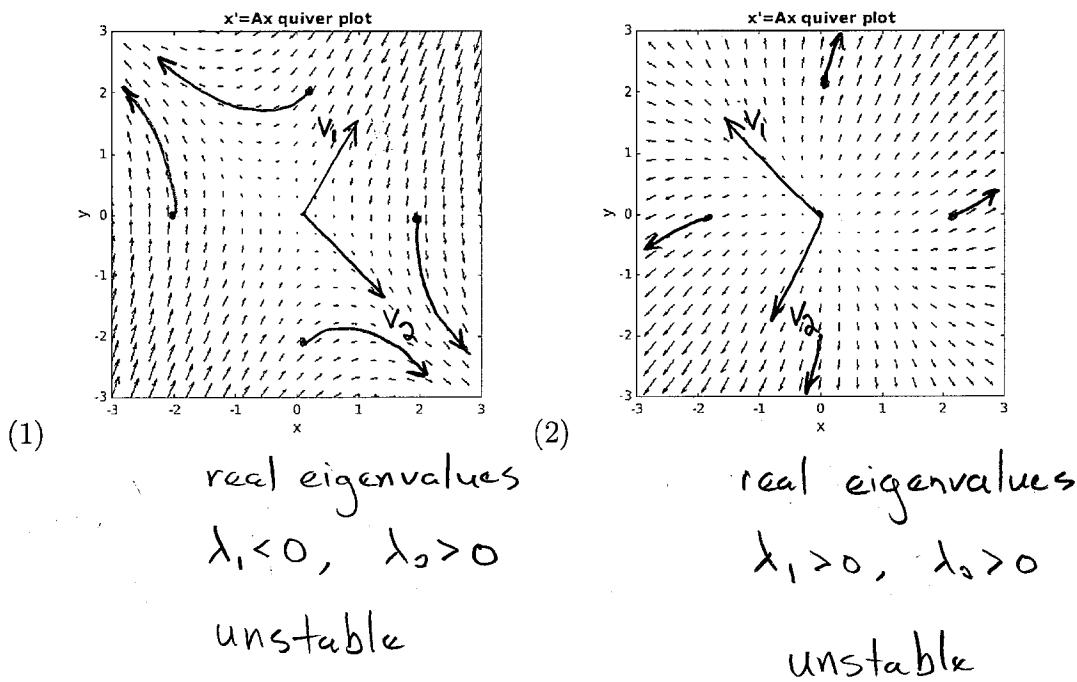
- Say whether the eigenvalues are real or complex.
- If the eigenvalues are real, draw the eigenvectors, label them \mathbf{v}_1 and \mathbf{v}_2 , and specify the signs of λ_1 and λ_2 (e.g. $\operatorname{Re} \lambda_1 < 0$, $\operatorname{Re} \lambda_2 > 0$).
- If the eigenvalues are complex, specify the sign of their real part (e.g. $\operatorname{Re} \lambda < 0$).
- Draw trajectories starting from the points $(x, y) = (2, 0), (0, 2), (-2, 0)$, and $(0, -2)$.
- If $\mathbf{x}(t) \rightarrow 0$ for all choices of initial conditions, then the system $\mathbf{x}' = A\mathbf{x}$ is said to be *stable*. If $\mathbf{x}(t) \rightarrow \infty$ for all but very special choices of initial conditions (such as $\mathbf{x}(0)$ lying exactly on an eigenvector), then the system is said to be *unstable*. Specify whether the system is stable or unstable.



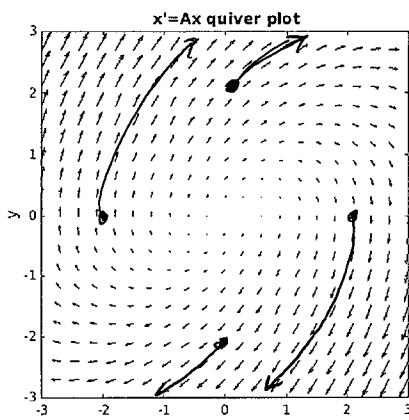
Note: The subscript labels are arbitrary + interchangeable
 What's important is that the eigvec pointing up+right has a negative eigenval, and the other has a positive eigenval.

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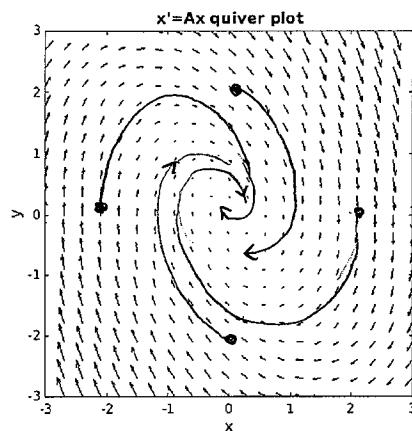


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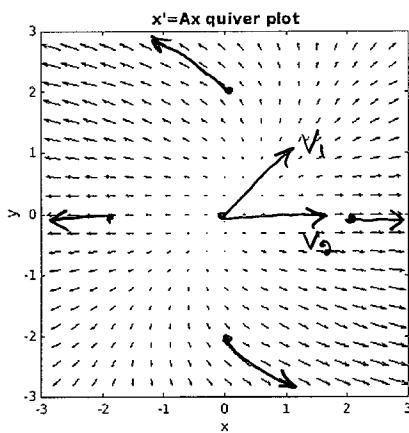
(3)

complex eigenvals
 $\text{Re } \lambda > 0$
 unstable



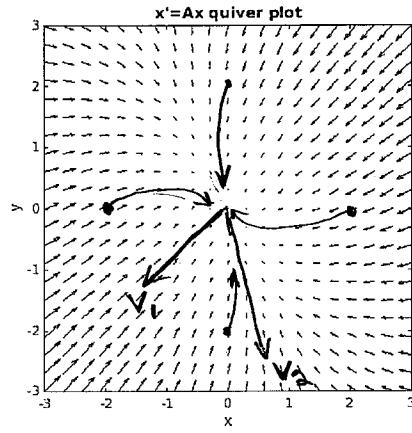
(4)

complex eigenvalues
 $\text{Re } \lambda < 0$
 stable



(5)

real eigenvalues
 $\lambda_1 > 0, \lambda_2 > 0$
 unstable



(6)

real eigenvalues
 $\lambda_1 < 0, \lambda_2 < 0$
 stable